



PEDESTRIAN DYNAMICS AND BOTTLENECK FLOW

Jonas Rzezonka (IAS-7), Forschungszentrum Jülich and Universität zu Köln

DATUM

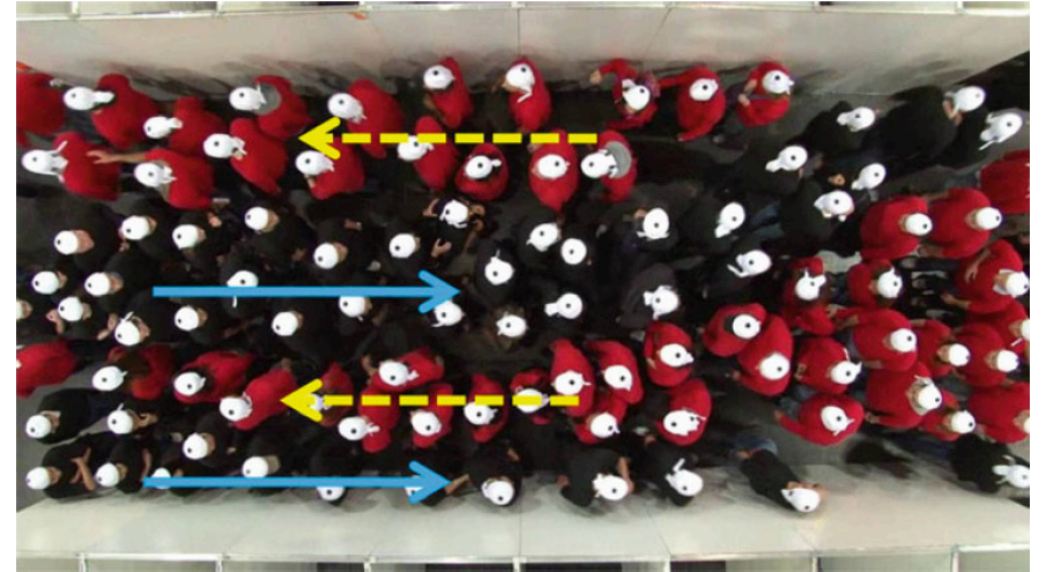


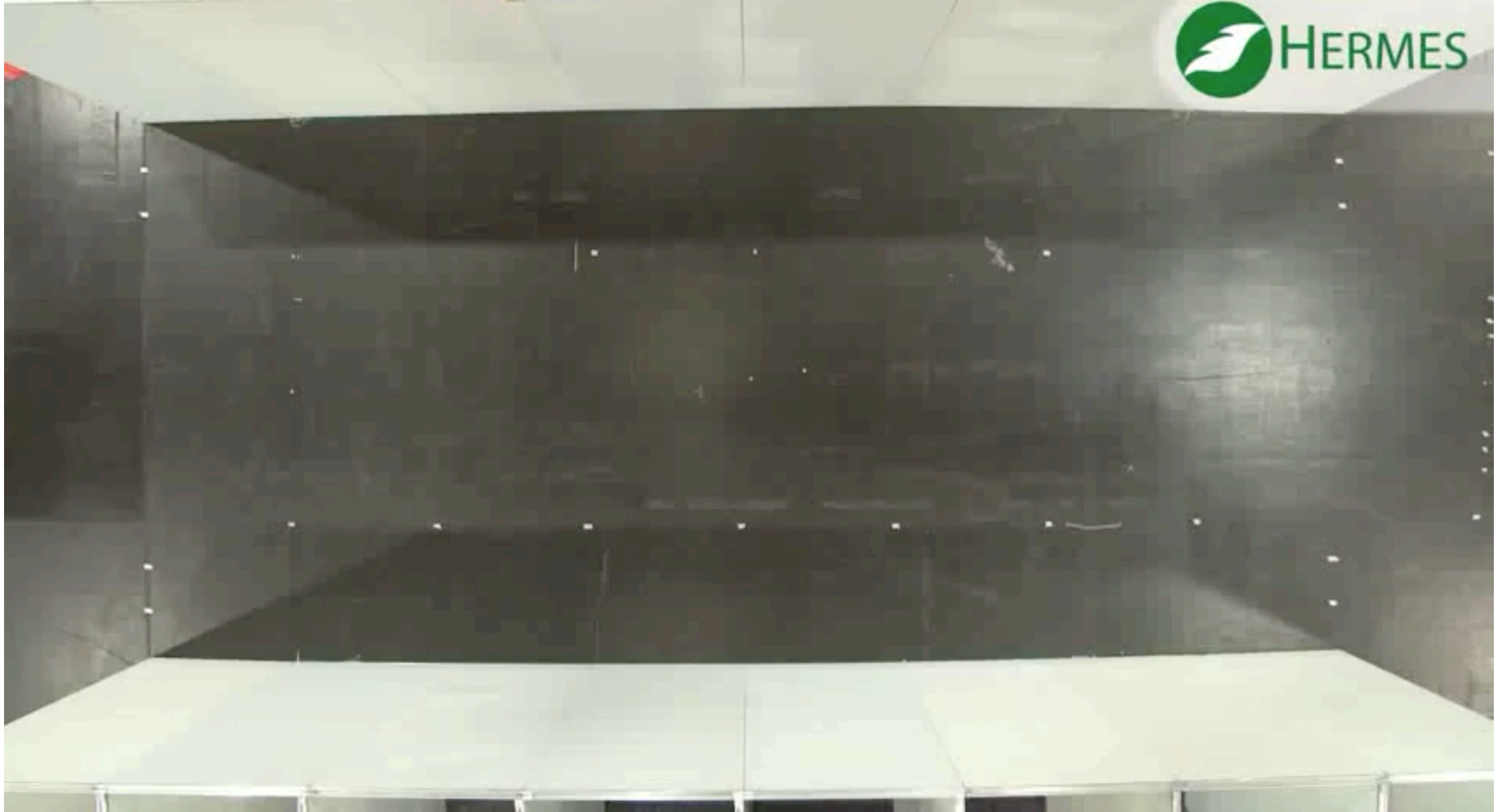
Source: Wikipedia.org

PHYSICS PERSPECTIVE

Self-organising phenomenon and collective effects

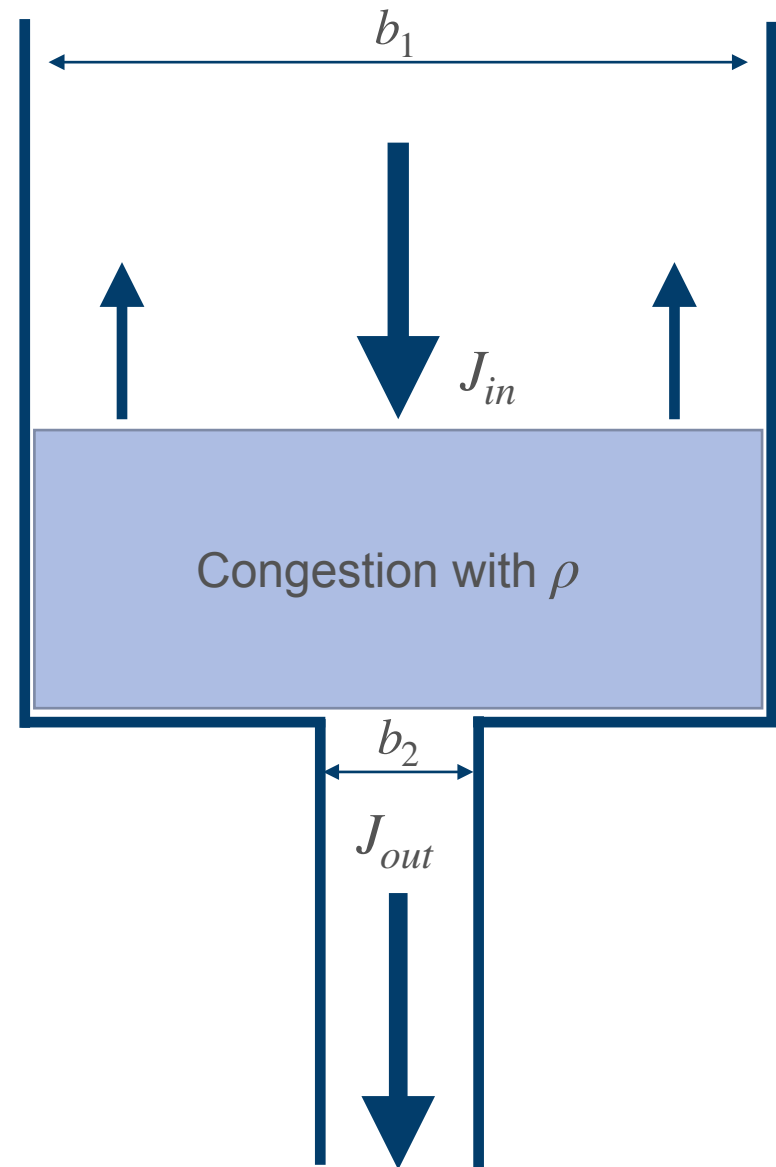
- Observe macroscopic effects that result from microscopic interaction
- Examples:
 - Lane formation in counterflow
 - Oscillation in counterflow at bottlenecks
 - Stop and go waves
 - Clogging and Jamming at Bottlenecks





BOTTLENECK SITUATION

- Process definition
 - Unidirectional movement of pedestrians passing a bottleneck
 - Incoming flow J_{in} vs. outgoing flow J_{out}
- Phenomena
 - $J_{in} > J_{out}$ leads to congestion
 - Density ρ increases till a threshold ρ^* when the congestion area grows in the opposite direction
 - Clogging



CLOGGING IN GRANULAR MATTER AND ARCHITECTURE



Immortal Bridge near Mount Tai in China



Roman aqueduct near Tunis

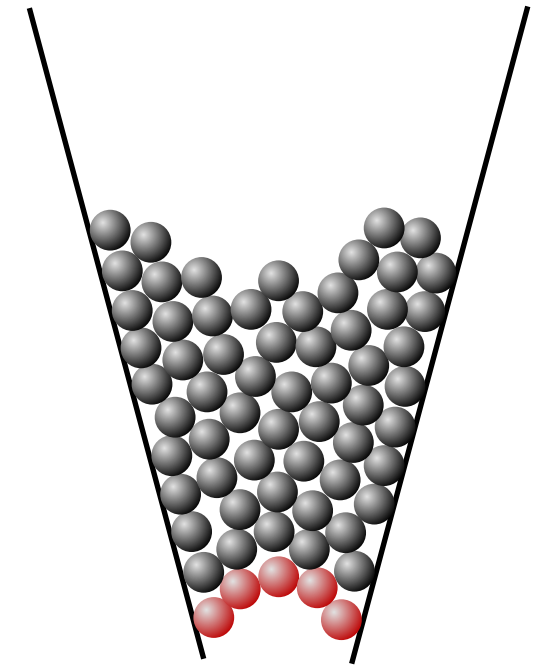


Illustration of clogging in granular matter

(source [wikipedia.org](https://www.wikipedia.org))

- Evacuation experiment through a bottleneck with sheep
- Narrow door leads to food source
- The sheep are highly motivated and show no cooperation
- Clogging occurs

MOTIVATION AND COOPERATION

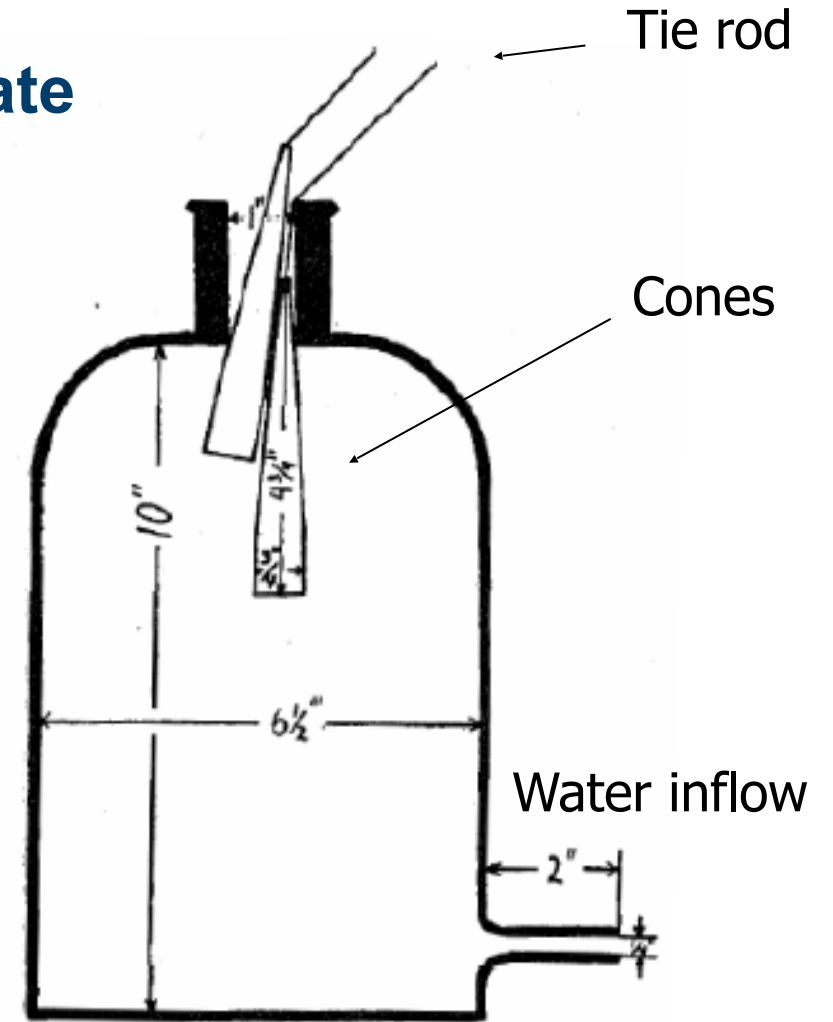
Motivation influences the insensitive to cooperate

- ▶ Experiment of Mintz
 - ▶ Groups of 15-21 students
 - ▶ Task: Pull out cones dry
 - ▶ only one cone at the time without clogging
- ▶ Different setups and instructions
 - ▶ With and without reward (money)
 - ▶ With and without opportunity to discuss
 - ▶ With and without special arousal (swearing and noise)

▶ Without reward: No clogging

▶ **With reward: clogging**

Source: A. Mintz, *Non-adaptive group behaviour*, The Journal of abnormal and social psychology 46 150 (1951)

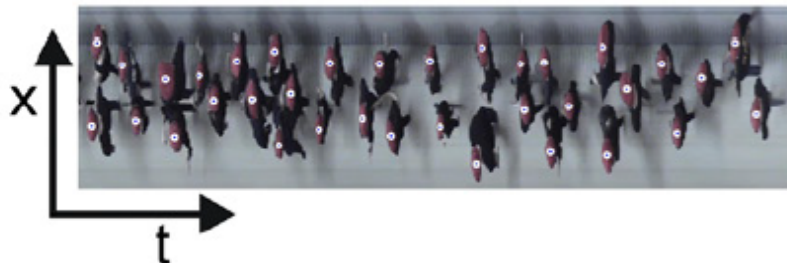
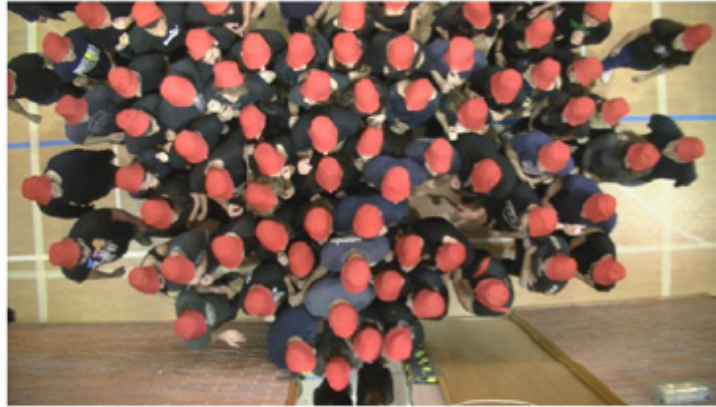


INFLUENCE OF MOTIVATION ON CLOGGING

Low motivation

Medium motivation

High motivation



Source: Garcimartín, Parisi, Pastor, Martín-Gómez, Zuriguel, *Flow of pedestrians through narrow doors with different competitiveness*, J. Stat. Mech, 043402, 2016

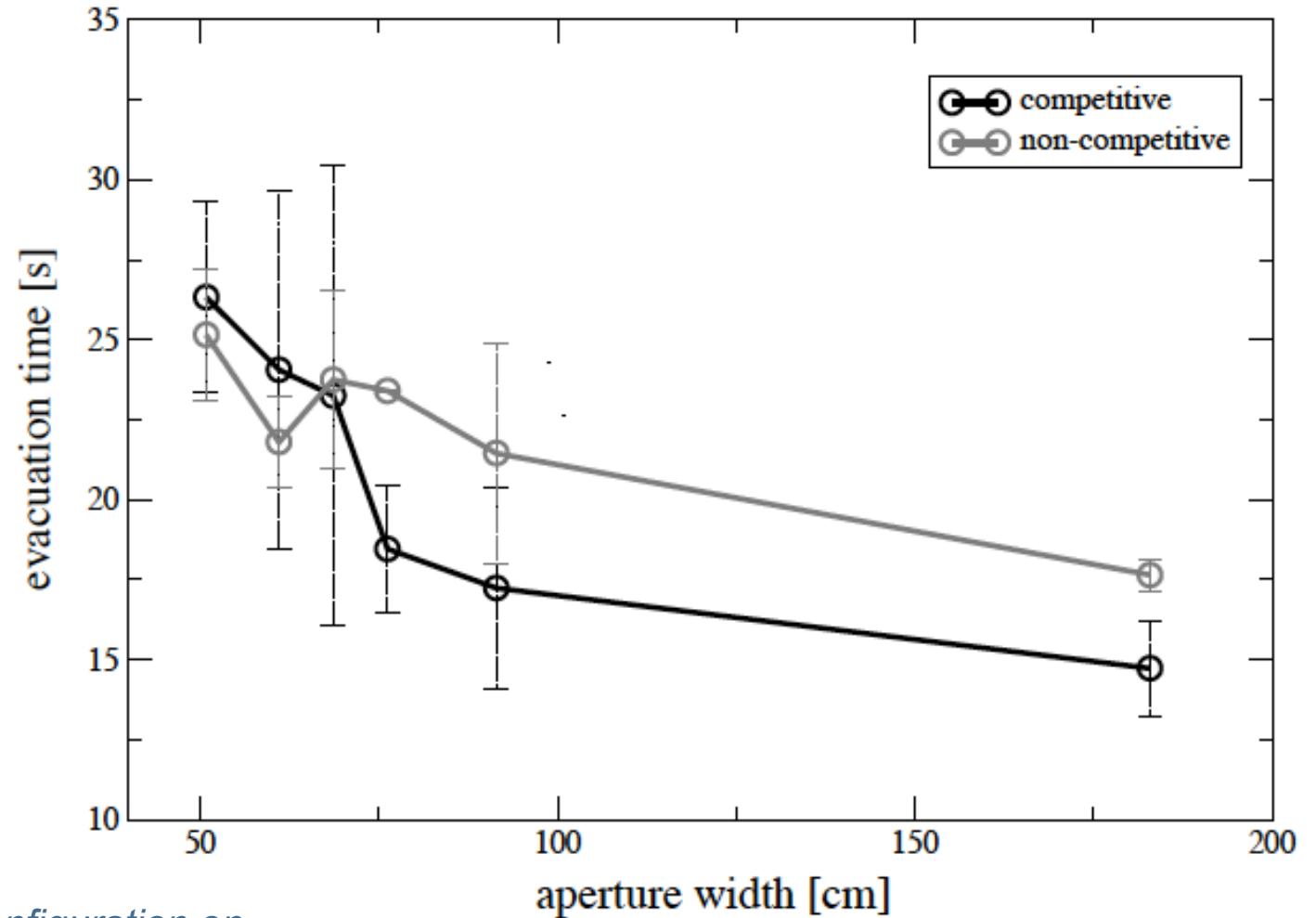
BOTTLENECK EXPERIMENT



Video: Experiments performed by Majid Sarvi, University of Melbourne, Australia, 2018

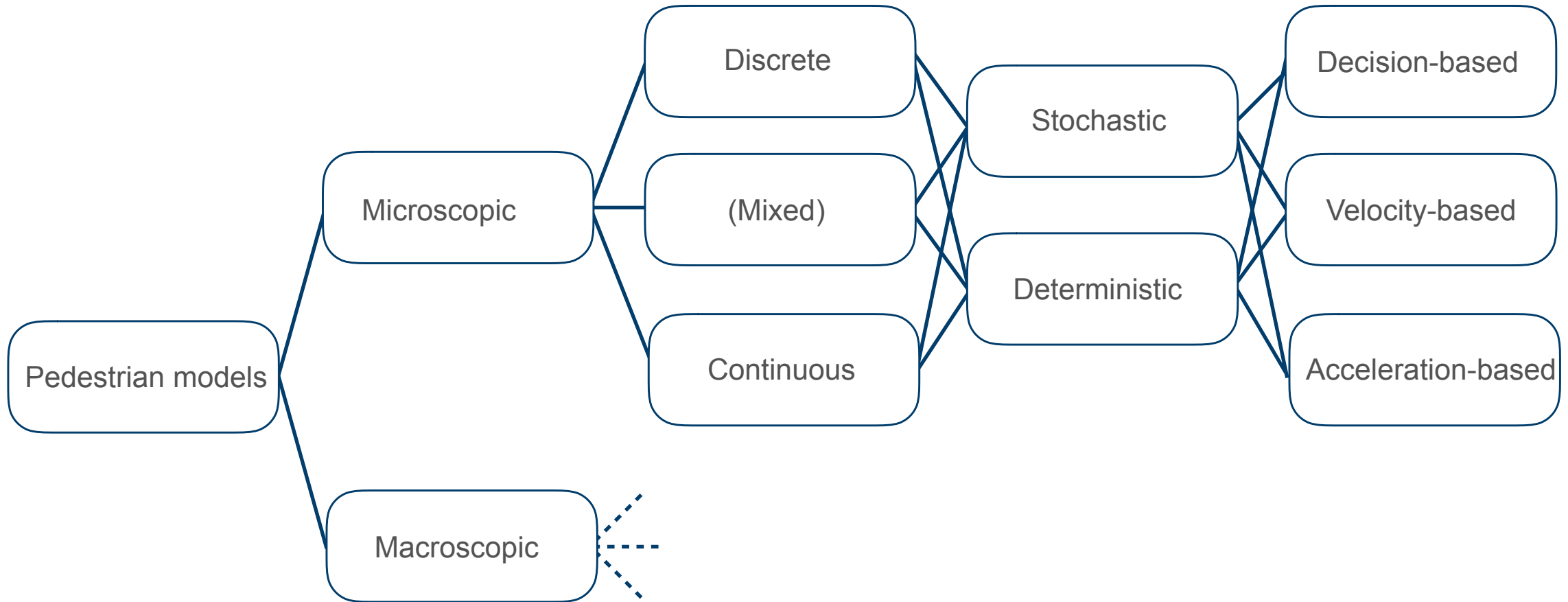
BOTTLENECK EXPERIMENT

- ▶ Evacuation of an aircraft
 - ▶ Competitive and non competitive situation (money as reward)
 - ▶ variable exit width w_c
 - ▶ $t_{comp} > t_{non-comp}$ if $w < w_c$
 - ▶ $t_{comp} < t_{non-comp}$ if $w > w_c$



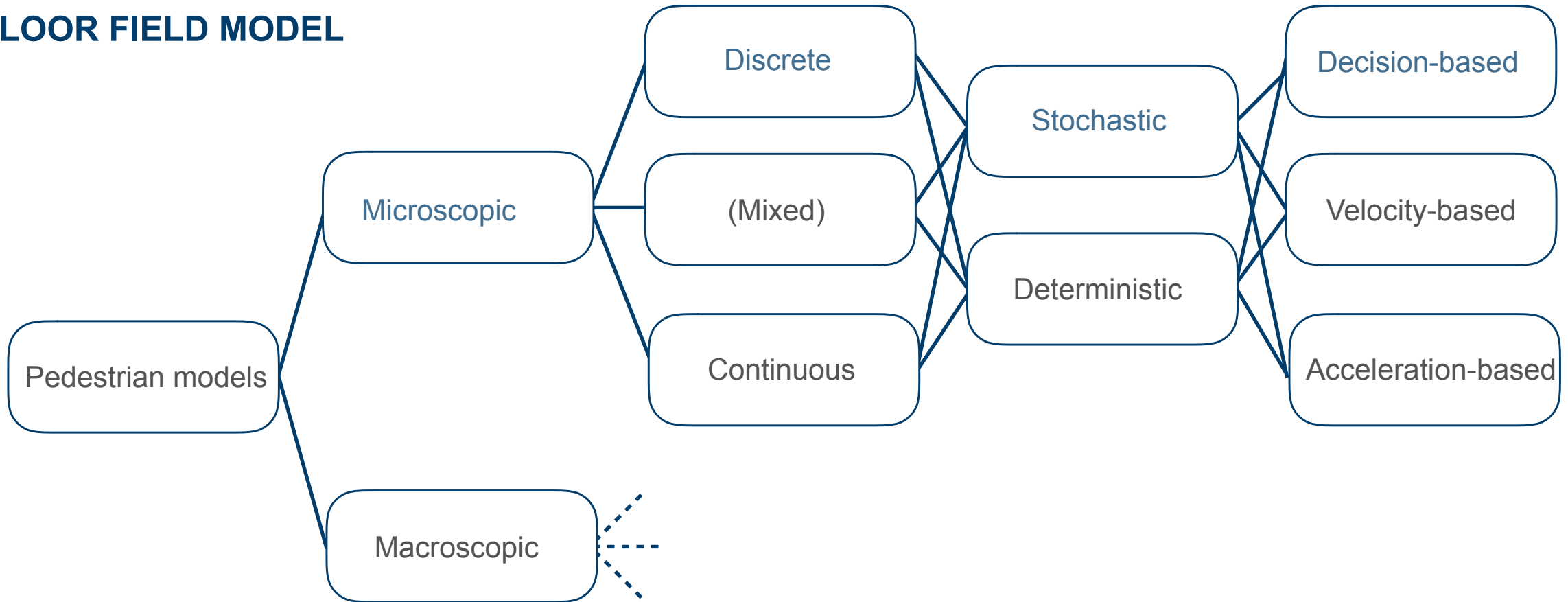
Source: Muir et al., *Effects of Motivation and Cabin Configuration on Emergency Aircraft Evacuation Behavior and Rates of Egress*, The Int. J. of Aviation Psychology, 6, 1996

MODELLING APPROACHES



MODELLING APPROACHES

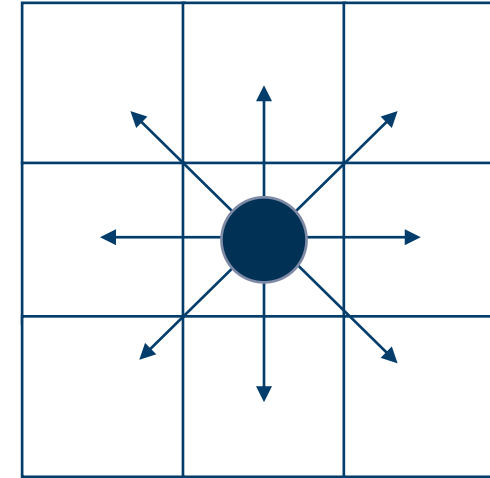
FLOOR FIELD MODEL



MODELLING APPROACHES

FLOOR FIELD MODEL

- ▶ Cellular automata model discrete in space and time with parallel dynamics
- ▶ Space is divided into cells which can only be occupied by a single agent
- ▶ At each time step an agent can transition to one of the neighbouring empty cells with a certain probability fixed by the *floor field*



$S_{-1,-1}$	$S_{-1,0}$	$S_{-1,1}$
$S_{0,-1}$	$S_{0,0}$	$S_{0,1}$
$S_{1,-1}$	$S_{1,0}$	$S_{1,1}$

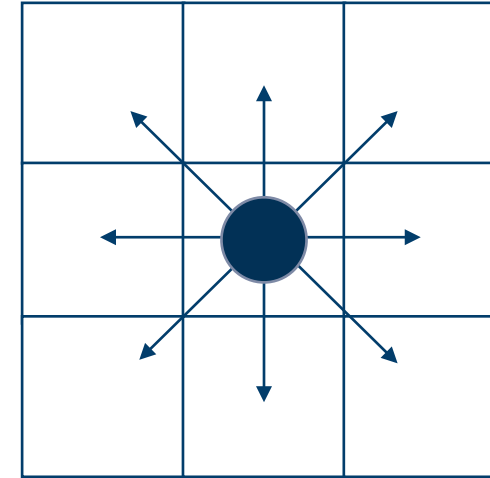
MODELLING APPROACHES

FLOOR FIELD MODEL

- ▶ Example: An empty cell closer to the destination has a higher transition probability than one further away

$$p_{ij} \propto (1 - n_{ij}) \exp(k_s S_{ij})$$

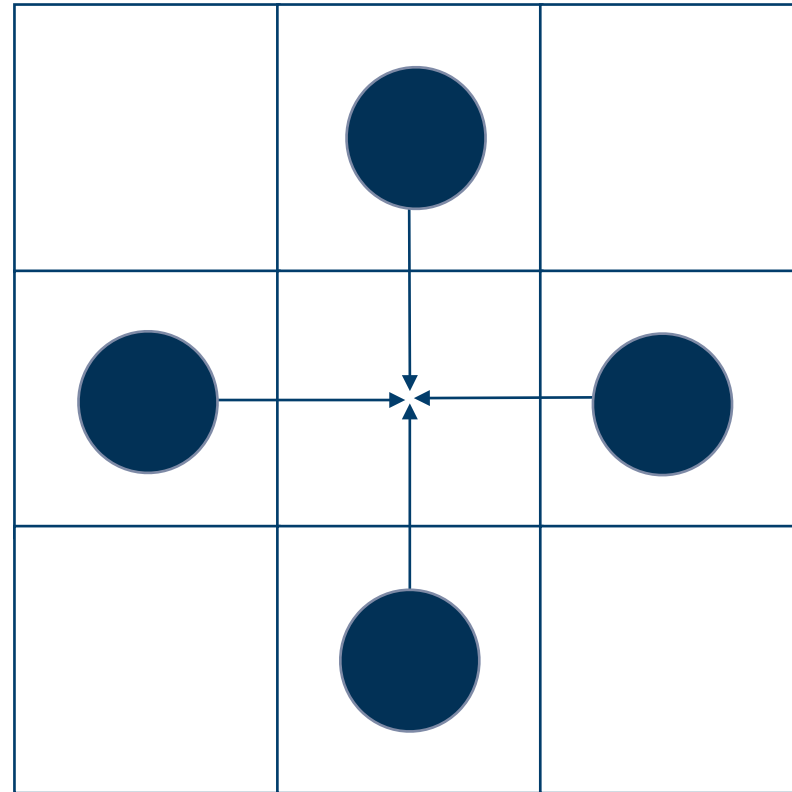
- ▶ $n_{ij} \in 0, 1$
 - ▶ 1 occupied, 0 unoccupied
- ▶ S_{ij} increases closer to destination
- ▶ k_s sensitivity parameter $[0, \infty)$



$S_{-1,-1}$	$S_{-1,0}$	$S_{-1,1}$
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MODELLING APPROACHES

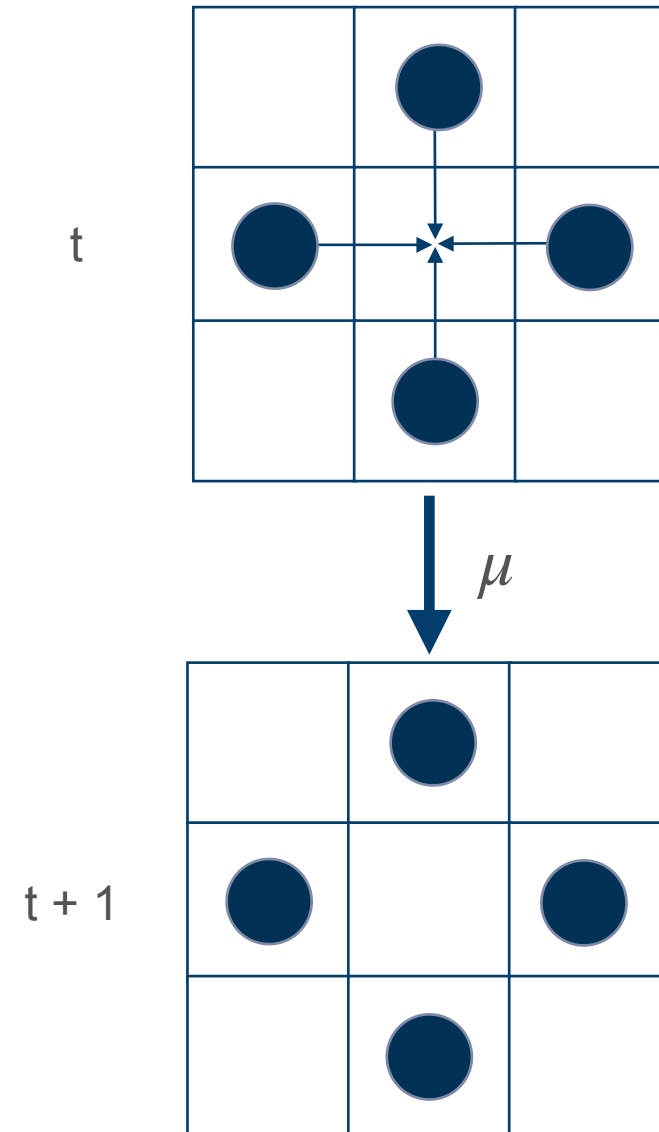
Floor field model with friction



MODELLING APPROACHES

Floor field model with friction

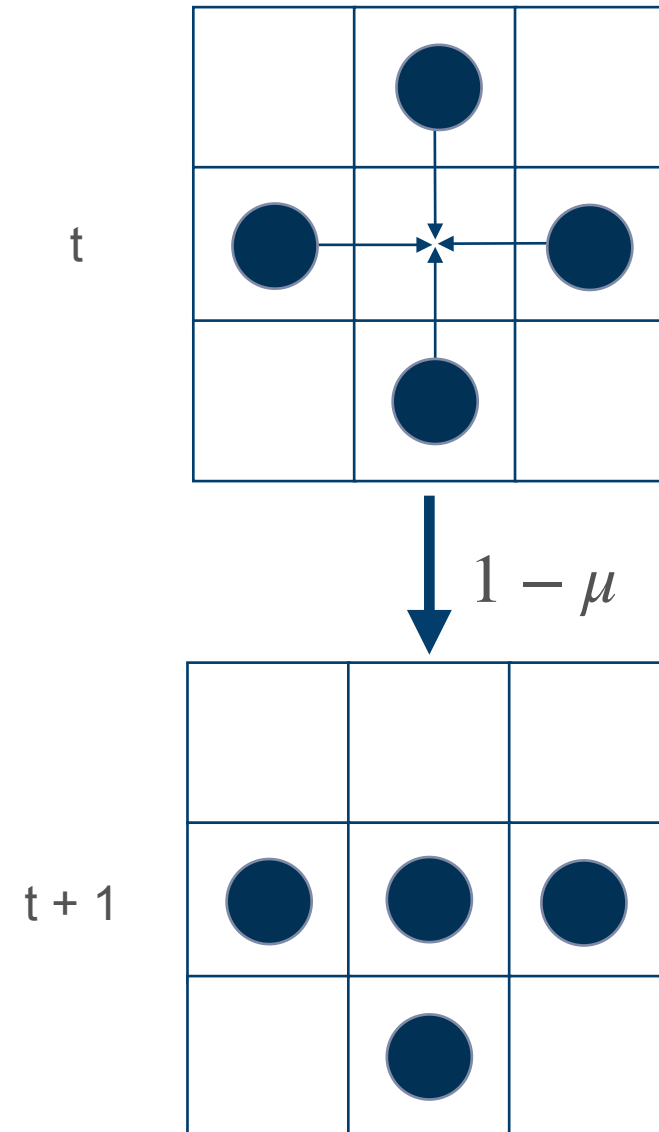
- Conflict resolution
 - No conflict: $p_{ij} \propto (1 - n_{ij})\exp(k_s S_{ij})$
 - Conflict: pedestrians can not move with probability μ
 - probability $1 - \mu$ one of the pedestrians can move into the cell
 - pedestrian chosen randomly with equal probability



MODELLING APPROACHES

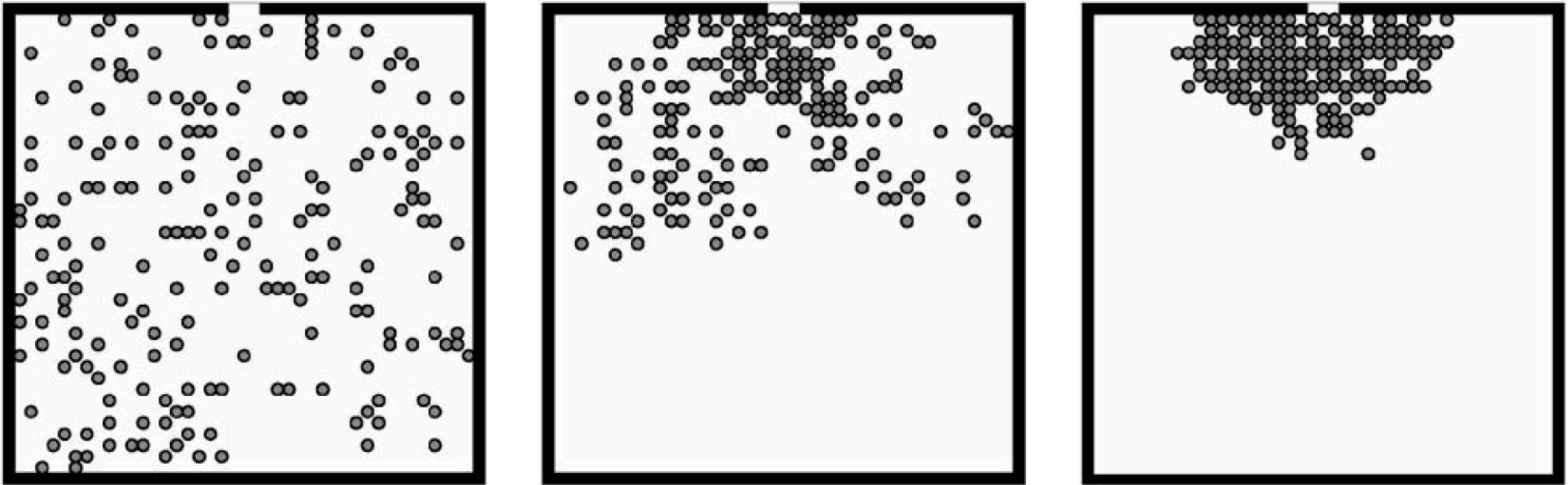
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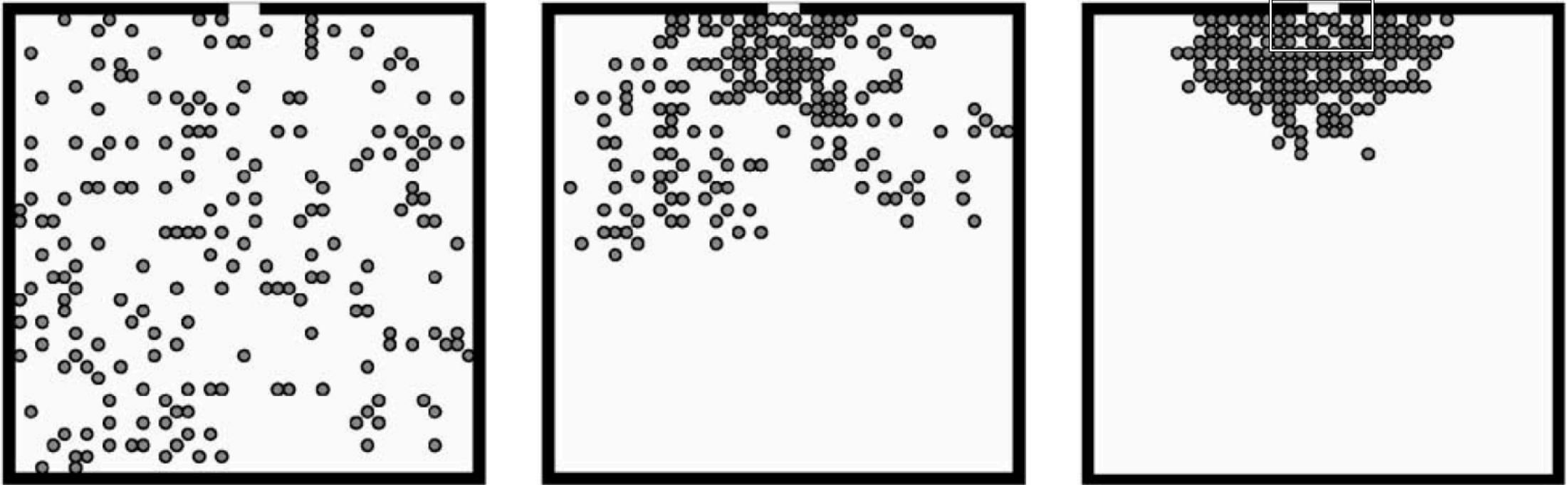
Illustration of a floor field simulation



Source: C. Bursedde, K.Klauck, A. Schadschneider, J. Zittartz (2001), *Simulation of pedestrian dynamics using a two-dimensional cellular automaton*, Physica A 295 (2001) 507–525

MODELLING APPROACHES

Illustration of a floor field simulation



Source: C. Bursedde, K.Klauck, A. Schadschneider, J. Zittartz (2001), *Simulation of pedestrian dynamics using a two-dimensional cellular automaton*, Physica A 295 (2001) 507–525

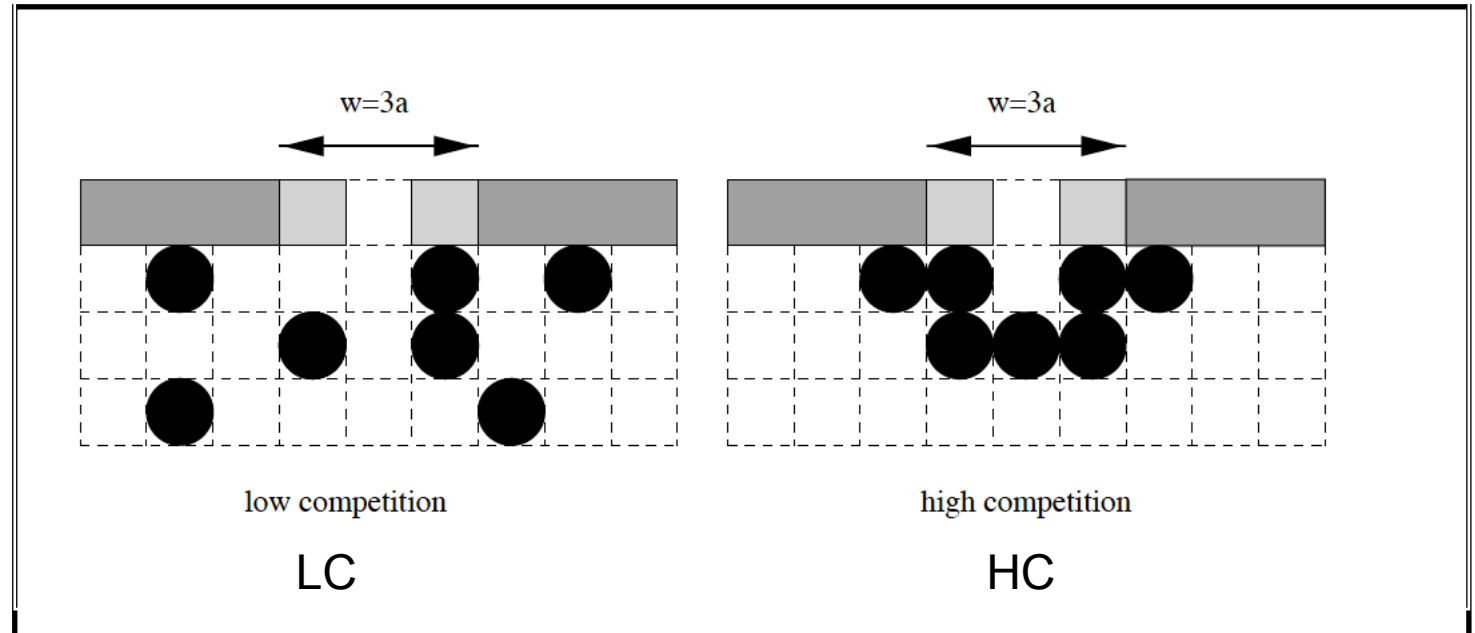
MODELLING APPROACHES

Illustration of a floor field simulation

$$p_{ij} \propto (1 - n_{ij}) \exp(k_s S_{ij})$$

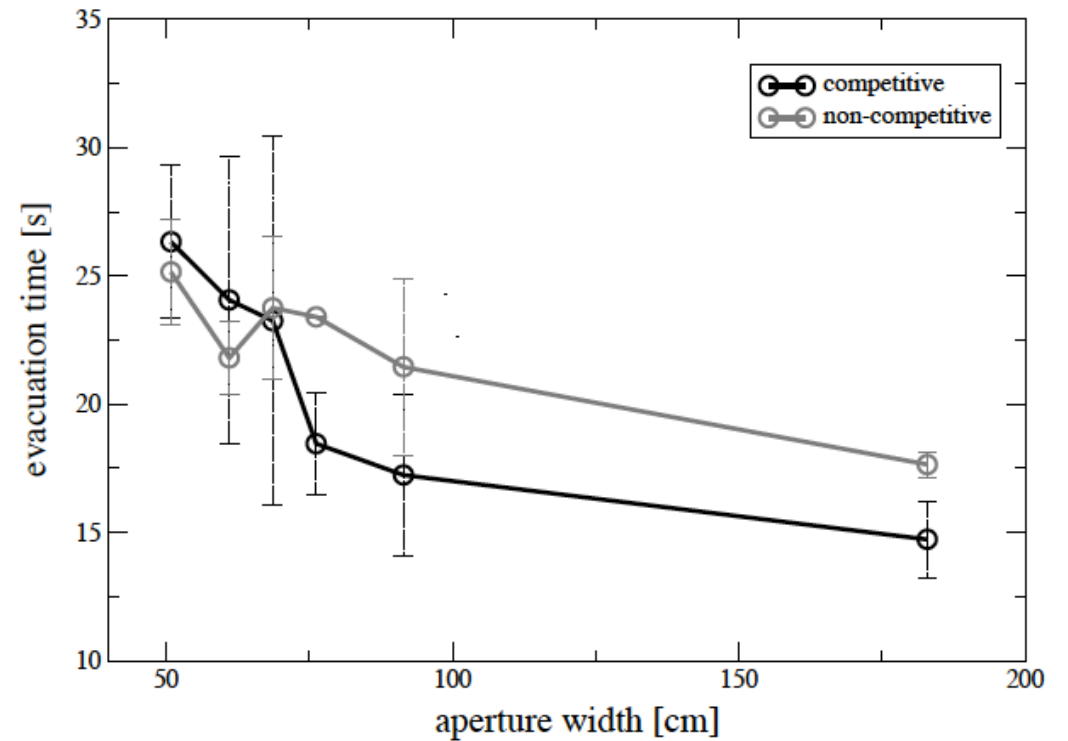
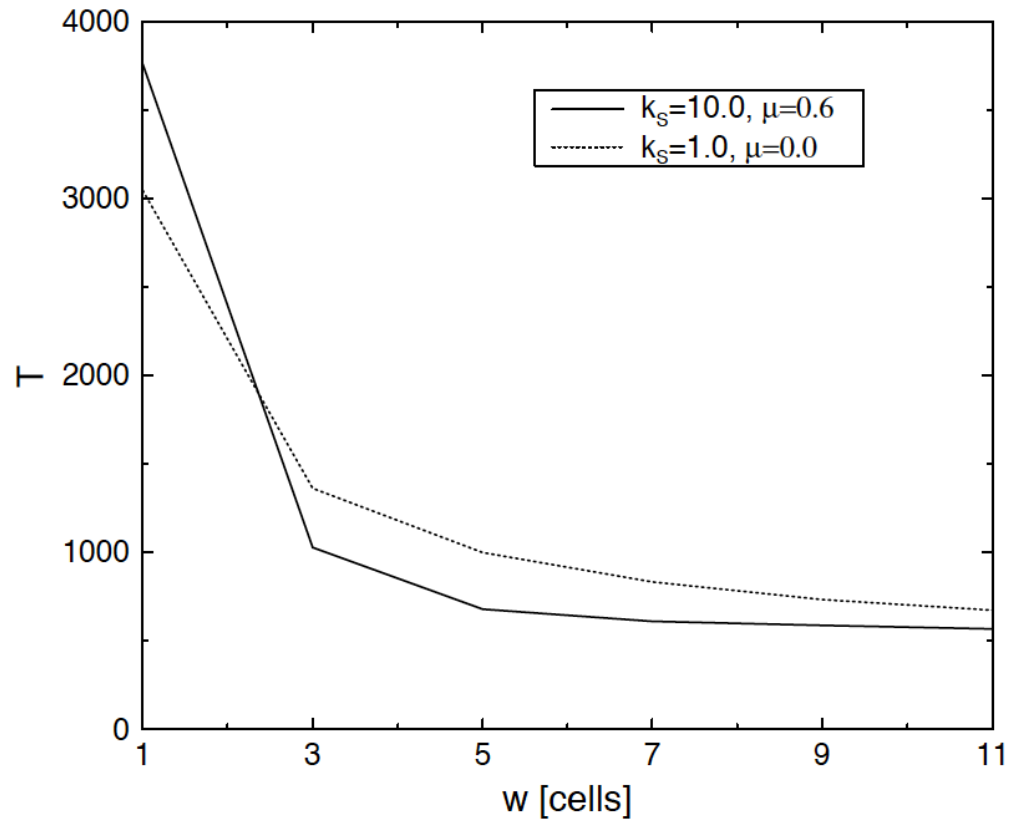
▸ $\mu_{LC} < \mu_{HC}$

▸ $k_{s,LC} < k_{s,HC}$



MODELLING APPROACHES

Illustration of a floor field simulation



SUMMARY

THANK YOU FOR LISTENING